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#### **CAMBRIDGE INTERNATIONAL EXAMINATIONS**

**International General Certificate of Secondary Education** 

## MARK SCHEME for the October/November 2013 series

# 0445 DESIGN AND TECHNOLOGY

0445/43

Paper 4 (Systems and Control), maximum raw mark 50

This mark scheme is published as an aid to teachers and candidates, to indicate the requirements of the examination. It shows the basis on which Examiners were instructed to award marks. It does not indicate the details of the discussions that took place at an Examiners' meeting before marking began, which would have considered the acceptability of alternative answers.

Mark schemes should be read in conjunction with the question paper and the Principal Examiner Report for Teachers.

Cambridge will not enter into discussions about these mark schemes.

Cambridge is publishing the mark schemes for the October/November 2013 series for most IGCSE, GCE Advanced Level and Advanced Subsidiary Level components and some Ordinary Level components.



Page 2	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

## Section A

1	(a)	Torsion/Torque	[1]
	(b)	Shear	[1]
	(c)	Factor of safety could be increased by:  using larger gauge screws  quality of wall plugs  using hardened screws  using more screws spread across the frame.  using washers under screw heads  Description including two of above points, 2 marks.  Allow 2 marks if one point well described/justified.	[2]
2		Natural shell structure – nut shells, eggs, honeycomb, shells of seafood.  Manufactured shell structure – drinks cartons/cans, car bodies.	[1] [1]
3		Any third order lever, effort between load and pivot [1], label [1].	[2]
4		Card shown folded or fold lines marked [1], capable of supporting a load [1].	[2]
5		Label on top of hook [1] Label on the guy rope for tension [1] Label on shear legs for compression [1] Allow tension in the rope holding the load.	[2]
6	(a)	<b>A</b> – spur gear [1], allow 'gear' or similar. <b>B</b> – Worm gear, [1].	[2]
	(b)	Reduction ratio is <b>48:1</b> . No mark for 1:48.	[1]
7	(a)	A crankshaft converts <b>rotary</b> motion to <b>reciprocating</b> motion or A crankshaft converts <b>reciprocating</b> motion to <b>rotary</b> motion.	[2]
	(b)	A <b>cam</b> will convert rotary motion to reciprocating motion.	[1]
8	(a)	Colour codes are used because: <ul> <li>components are physically very small; it would be difficult to read print</li> <li>they can be read regardless of the orientation of the component on a PCB Allow any other valid response.</li> </ul>	[1]
	(b)	560 K colour code is <b>green</b> – blue – <b>yellow</b> . 2 × 1 marks	[2]

Page 3	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

9 Connections to NC [1] and C [1]



[2]

**10 0.1 μF 100 nF,** 2 marks, no marks for any other combination.

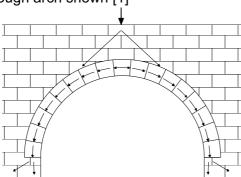
[2]

[Total: 25]

Page 4	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

### **Section B**

**11 (a)** Force through bricks distributed [1] Force through arch shown [1]



(b) (i) Strain gauge 1 will measure tension [1] Strain gauge 2 will measure compression [1]

[2]

(ii) The markings are to allow accurate alignment of the strain gauge.

[1]

[2]

(c) (i) Point A is elastic limit [1] allow mark for understanding shown. Point B is upper yield point, allow yield point [1] Allow marks for understanding shown.

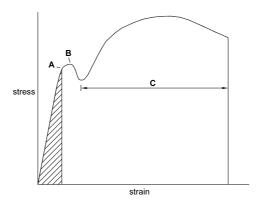
[2]

(ii) Section indicated by C is area of plastic deformation.

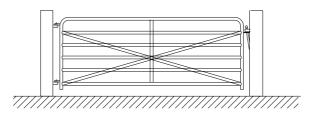
[1]

(iii) Single point on graph indicated [1]. Clear indication of area showed [1].

[2]



(d) (i) Triangulation used [1], Central support(s) to stop bending of horizontals [1]



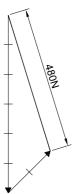
(ii) Indication of welding/bolts/rivets [1]

[1]

[2]

Page 5	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

(e) Resultant force 479.89 N. Allow either calculation/triangle/parallelogram method. Suitable method chosen [1], accurate drawing/scale used [1] correct result [1]. [3]



(f) Suitable joining method plates / scarf joint [1] Method of fixing shown screws / bolts / glue / wedges [1] Will keep two pieces in horizontal alignment [1] Will keep two pieces in vertical alignment [1]. 4 × 1 marks.

[4]

(g) (i) A moment is force × distance [1].

[1]

(ii) Moments about A: Reaction at **B** x 9 =  $(3 \times 900) + (7 \times 500)$  [1] Reaction at **B** 

= (2700 + 3500) / 9

= 688.89 N [1]

Reaction at A = 1400 - 688.89 = 711.11 N [1][4]

[Total: 25]

- **12** (a) Examples of energy loss could include:
  - Heat transformer, charging battery, motor, gears
  - Sound motor, reduction gears, output shaft
  - Friction motor, reduction gears, output shaft

3 × 1 marks for any three points included.

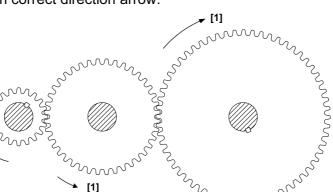
Type of energy involved must be given to gain each mark.

[3]

(b) Benefit of operating from batteries – Can be operated remotely, safer than mains power, no cables to get tangled, cause trip hazard. 1 mark for any suitable benefit, reduced cost must be justified. [1] Drawback – constant level of output from the transformer, battery output will decrease as charge drops or will fail suddenly. Battery output may be too low to operate the system. 1 mark for any suitable drawback. [1]

Page 6	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

(c) (i) 1 mark for each correct direction arrow.



- (ii) Gear ratio is 3:1, gear C rotates at 20 rpm.
- (iii) Gear B, the idler gear can rotate freely [1], as it is not being driven by its shaft or transferring drive to its shaft [1], 2 marks for clear explanation.1 mark for reference to free rotation being possible.[2]
- (d) (i) Ratchet and pawl.
  - (ii) Jack has to open a distance of 350 180 = 170 mm [1]
  - Pitch of screw is 5 mm, therefore 34 turns needed [1].

    (iii) Effort could be reduced by:
    Ensuring all parts are oiled/greased and move freely

Smaller pitch on the thread will reduce effort but require more turns Extending the lever used to operate the jack

2 × 1 marks. [2]

(e) (i) Benefit of:

Ball race – reduced contact area, can resist thrust, easily replaced. Roller race – reduced contact area, will take greater radial load than ball bearing. Plain bearing – low cost, can be pre oiled, can resist thrust.

3 × 1 marks, allow other valid benefits. [3]

- (ii) A nylon bearing will be self lubricating, lower cost, easy to produce in bulk. [1]
- (iii) Nylon has a relatively low melting point [1] and high speed rotation could melt the bearing [1].
- (f) (i) A bell crank lever will transfer motion through an angle, normally 90° [1].

  Operated by wire for pulling action or rod for pushing action [1], 2 × 1 marks. [2]
  - (ii) Mechanical advantage will be gained by moving linkage to position B [1].

    More movement of input link will be needed to move the output link the same distance as previously [1]

    [2]

[Total: 25]

[2]

[1]

[1]

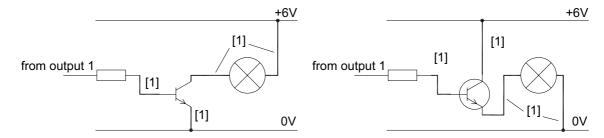
[2]

Page 7		7	Mark Scheme	Syllabus	Paper
			IGCSE – October/November 2013	0445	43
13	(a) (i)	Silve	er [1] Brass [1] Tin [1], 3 × 1 marks.		[3]
	(ii)	(ii) Component containing a semiconductor could be transistor/diode/IC.		[1]	
	(iii) Explanation should mention no moving mechanical parts, ease of assert switches are on one part, tactile action, lower cost than mechanical switch problem with arcing/oxidising of contacts. Response with two points mentioned 2 marks. Allow 2 marks for a clear explanation of one point.				
	(b) (i)	Moto Whe	and NO contacts are joined each junction going to a contacts are connected to common terminals of each switch is operated the motor connections to power warks for understanding shown. 2 × 1 marks for a	each switch [1]. er are reversed [1]	
	(ii)	<ul><li> C</li><li> b</li><li> M</li><li> D</li><li> a</li><li> T</li></ul>	antages of relay circuit could be: Connecting through a relay allows driver circuit volue different. Motor circuit will run at higher current. Oriver circuit and motor circuit are isolated so no infect the driver circuit. Two switches can be operated electronically by a sineark for valid advantage.	nterference from	-
	(c) (i)		es can differ in size, shape, intensity, angle of light Allow any other valid difference, 2 × 1 marks.	output, frequency	of light emitted [2]
	(ii)		- 1.8 V = <b>4.2 V</b> [1] Substitution into formula R = V/I R <b>280 <math>\Omega</math></b> [1] Correct answer with no working [3].	= 4.2 / .015 [1]	[3]
	(d) (i)	Res	istance in the strain gauge will change.		[1]
	(ii)	Volta	RC and RB / strain gauge are potential dividers [1] age across the centre of each will change from 0 ge changes [1]. Voltmeter will measure change in vo	V when resistan	ce in the strain

Page 8	Mark Scheme	Syllabus	Paper
	IGCSE – October/November 2013	0445	43

(e) (i) AND gates [1], NOT gates or inverters [1].

- [2]
- (ii) When switch 1 is pressed a logic 1 signal goes to AND gate A the other input is from NOT gate D which is a logic 1 signal, this makes the output of gate A logic 1 [1] As soon as gate A output has changed NOT gate C will send a logic 0 signal to an input of AND gate B preventing the gate from giving a logic 1 output [1]. Allow marks for understanding of each stage, 2 × 1 marks.
- (iii) Resistor to transistor base [1], emitter to 0 V [1], two lamp connections [1].
   3 × 1 marks for correct answer, any incorrect connections maximum of 2 marks. Emitter follower circuit can be used.
   [3]



[Total: 25]